

Order

Now



TPS3851-Q1

SBVS286-MARCH 2017

TPS3851-Q1 High-Accuracy Voltage Supervisor with Integrated Watchdog Timer

Technical

Documents

Features 1

- AEC-Q100 Qualified with the Following Results:
 - Device Temperature Grade 1: –40°C to 125°C Ambient Operating Temperature Range
 - **Device HBM ESD Classification Level 2**
 - Device CDM ESD Classification Level C4B
- Input Voltage Range: $V_{DD} = 1.6$ V to 6.5 V
- 1% Voltage Threshold Accuracy
- Low Supply Current: $I_{DD} = 10 \ \mu A \ (typ)$
- User-Programmable Watchdog Timeout
- Factory Programmed Precision Watchdog and **Reset Timers:**
 - ±15% Accurate WDT and RST Delays
- **Open-Drain Outputs**
- Precision Undervoltage Monitoring:
 - Supports Common Rails from 1.8 V to 5.0 V
 - 4% and 7% Undervoltage Thresholds Available
 - 0.5% Hysteresis
- Watchdog Disable Feature
- Available in a Small 3-mm × 3-mm, 8-Pin VSON Package

2 Applications

- Safety Critical Applications
- Automotive Vision Systems
- Automotive ADAS Systems
- **Telematics Control Units**
- **FPGAs and ASICs**
- Microcontrollers and DSPs

3 Description

Tools &

Software

The TPS3851-Q1 device combines a precision voltage supervisor with a programmable watchdog timer. The TPS3851-Q1 comparator achieves a 0.8% accuracy (-40°C to +125°C) for the undervoltage (VITN) threshold. The TPS3851-Q1 also includes accurate hysteresis on the undervoltage threshold making the device ideal for use with tight tolerance systems. The supervisor RESET delay features a 15% accuracy, high-precision delay timing.

Support &

Community

2.0

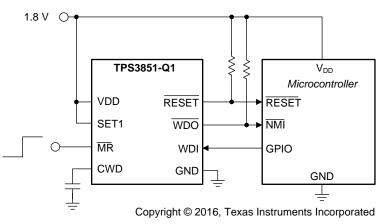
The TPS3851-Q1 includes а programmable watchdog timer for a wide variety of applications. The dedicated watchdog output (WDO) enables increased resolution to help determine the nature of fault conditions. The watchdog timeouts can be programmed either by an external capacitor, or by factory-programmed default delay settings. The watchdog can be disabled via logic pins to avoid undesired watchdog timeouts during the development process.

The TPS3851-Q1 is available in a small 3.00-mm × 3.00-mm, 8-pin VSON package. The TPS3851-Q1 features wettable flanks that allow for easy optical inspection.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
TPS3851-Q1	VSON (8)	3.00 mm × 3.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.



Typical Application Circuit



Texas Instruments

www.ti.com

Table of Contents

1	Feat	tures	1				
2	Арр	Applications 1					
3	Des	cription	1				
4	Rev	ision History	2				
5	Pin	Configuration and Functions	3				
6	Spe	cifications	4				
	6.1	Absolute Maximum Ratings	4				
	6.2	ESD Ratings	4				
	6.3	Recommended Operating Conditions	4				
	6.4	Thermal Information					
	6.5	Electrical Characteristics	5				
	6.6	Timing Requirements					
	6.7	Typical Characteristics	8				
7	Deta	ailed Description 1	11				
	7.1	Overview	11				
	7.2	Functional Block Diagram	11				
	7.3	Feature Description	12				

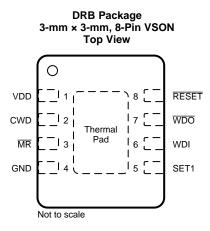
	7.4	Device Functional Modes	14
8	Арр	lication and Implementation	15
	8.1	Application Information	15
	8.2	Typical Application	18
9	Pow	er Supply Recommendations	21
10	Lay	out	21
	10.1	Layout Guidelines	21
	10.2	Layout Example	21
11	Dev	ice and Documentation Support	22
	11.1	Device Support	22
	11.2	Documentation Support	22
	11.3	Receiving Notification of Documentation Updates	22
	11.4	Community Resources	22
	11.5	Trademarks	22
	11.6	Electrostatic Discharge Caution	22
	11.7	Glossary	23
12		hanical, Packaging, and Orderable	
	Info	rmation	23

4 Revision History

DATE	REVISION	NOTES
March 2017	*	Initial release.



5 Pin Configuration and Functions



Pin Functions

NAME	NO.	I/O	DESCRIPTION
CWD	2	Programmable watchdog timeout input. The watchdog timeout is set by connecting a capacitor between this pin and ground. Connecting via a 10-kΩ resistor to V_{DD} or leaving unconnected further enables the selection of the preset watchdog timeouts; see the <i>CWD Functionality</i> section. The TPS3851-Q1 determines the watchdog timeout using either Equation 1 or Equation 2 with standard or extended timing, respectively.	
GND	4		Ground pin
MR	3	I	Manual reset pin. A logical low on this pin issues a $\overline{\text{RESET}}$. This pin is internally pulled up to V _{DD} . $\overline{\text{RESET}}$ remains low for a fixed reset delay (t _{RST}) time after MR is deasserted (high).
RESET	ET 8 O RESET goes low when V _{DD} goes below the undervoltage threshold (V _{ITN}). When V _{DD} is within the operating range, the RESET timeout-counter starts. At completion, RESET goes high. During star state of RESET is undefined below the specified power-on-reset (POR) voltage (V _{POR}). Above POR RESET goes low and remains low until the monitored voltage is within the correct operating range		$ \begin{array}{l} \hline Reset \mbox{ output. Connect \overline{RESET} using a 1-k\Omega to 100-k\Omega$ resistor to the correct pullup voltage rail (V_{PU}). \\ \hline RESET \mbox{ goes low when V_{DD} goes below the undervoltage threshold (V_{ITN}). When V_{DD} is within the normal operating range, the $RESET$ timeout-counter starts. At completion, $RESET$ goes high. During startup, the state of $RESET$ is undefined below the specified power-on-reset (POR) voltage (V_{POR}). Above POR, $RESET$ goes low and $remains$ low until the monitored voltage is within the correct operating range (above $V_{ITN} + V_{HYST}$) and the $RESET$ timeout is complete. \\ \hline \end{array}$
SET1	5	I	Logic input. Grounding the SET1 pin disables the watchdog timer. SET1 and CWD select the watchdog timeouts; see the SET1 section.
VDD	1	I	Supply voltage pin. For noisy systems, connecting a 0.1-µF bypass capacitor is recommended.
WDI	6	I	Watchdog input. A falling edge must occur at WDI before the timeout (t_{WD}) expires. When the watchdog is not in use, the SET1 pin can be used to disable the watchdog. WDI is ignored when RESET or WDO are low (asserted) and when the watchdog is disabled. If the watchdog is disabled, WDI cannot be left unconnected and must be driven to either VDD or GND.
WDO	7	0	$ \begin{array}{l} \hline Watchdog \mbox{ output. Connect } \overline{WDO} \mbox{ with a 1-k}\Omega \mbox{ to 100-k}\Omega \mbox{ resistor to the correct pullup voltage rail } (V_{PU}). \\ \hline WDO \mbox{ goes low (asserts) when a watchdog timeout occurs. WDO \mbox{ only asserts when RESET is high. When a watchdog timeout occurs, WDO \mbox{ goes low (asserts) when a watchdog timeout occurs) for the set RESET timeout \mbox{ delay } (t_{RST}). When RESET \mbox{ goes low, WDO is in a high-impedance state.} \end{array} $
Thermal pad		—	Connect the thermal pad to a large-area ground plane. The thermal pad is internally connected to GND.

6 Specifications

6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

		MIN	МАХ	UNIT
Supply voltage range	VDD	-0.3	7	V
Output voltage range	RESET, WDO	-0.3	7	V
Voltage reages	SET1, WDI, MR	-0.3	7	V
Voltage ranges	CWD	-0.3	$V_{DD} + 0.3^{(2)}$	v
Output pin current	RESET, WDO		±20	mA
Input current (all pins)			±20	mA
Continuous total power dissipation	Continuous total power dissipation		nal Information	
	Operating junction, $T_J^{(3)}$	-40	150	
Temperature	Operating free-air, T _A ⁽³⁾	-40	150	°C
	Storage, T _{stg}	-65	150	

Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings (1) only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

The absolute maximum rating is V_{DD} + 0.3 V or 7.0 V, whichever is smaller. (2)

Assume that $T_J = T_A$ as a result of the low dissipated power in this device. (3)

6.2 ESD Ratings

			VALUE	UNIT
V	Electrostatio discharge	Human-body model (HBM), per AEC Q100-002 ⁽¹⁾	±2000	V
V _(ESD)	Electrostatic discharge	Charged-device model (CDM), per AEC Q100-011	±750	v

(1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	TYP	MAX	UNIT
V _{DD}	Supply pin voltage	1.6		6.5	V
V _{SET1}	SET1 pin voltage	0		6.5	V
C _{CWD}	Watchdog timing capacitor	0.1 ⁽¹⁾⁽²⁾		1000 ⁽¹⁾⁽²⁾	nF
CWD	Pullup resistor to VDD	9	10	11	kΩ
R _{PU}	Pullup resistor, RESET and WDO	1	10	100	kΩ
IRESET	RESET pin current			10	mA
IWDO	Watchdog output current			10	mA
TJ	Junction temperature	-40		125	°C

(1)

Using standard timing with a C_{CWD} capacitor of 0.1 nF or 1000 nF gives a $t_{WD(typ)}$ of 0.704 ms or 3.23 seconds, respectively. Using extended timing with a C_{CWD} capacitor of 0.1 nF or 1000 nF gives a $t_{WD(typ)}$ of 62.74 ms or 77.45 seconds, respectively. (2)

6.4 Thermal Information

		TPS3851-Q1	
	THERMAL METRIC ⁽¹⁾	DRB (VSON)	UNIT
		8 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	47.7	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	51.5	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	22.2	°C/W
ΨJT	Junction-to-top characterization parameter	1.3	°C/W
Ψјв	Junction-to-board characterization parameter	22.3	°C/W
R _{0JC(bot)}	Junction-to-case (bottom) thermal resistance	4.3	°C/W

(1) For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

6.5 Electrical Characteristics

at $V_{\text{ITN}} + V_{\text{HYST}} \le V_{\text{DD}} \le 6.5$ V over the operating temperature range of $-40^{\circ}\text{C} \le T_{\text{A}}$, $T_{\text{J}} \le 125^{\circ}\text{C}$ (unless otherwise noted); the open-drain pullup resistors are 10 k Ω for each output; typical values are at $T_{\text{J}} = 25^{\circ}\text{C}$

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
GENERAL (CHARACTERISTICS					
V _{DD} ⁽¹⁾⁽²⁾⁽³⁾	Supply voltage		1.6		6.5	V
I _{DD}	Supply current			10	19	μΑ
RESET FUN	ICTION					
V _{POR} ⁽²⁾	Power-on reset voltage	$I_{\overline{\text{RESET}}}$ = 15 µA, $V_{OL(MAX)}$ = 0.25 V			0.8	V
V _{UVLO} ⁽¹⁾	Undervoltage lockout voltage			1.35		V
V _{ITN}	Undervoltage threshold accuracy, entering RESET	V _{DD} falling	V _{ITN} – 0.8%		V _{ITN} + 0.8%	
V _{HYST}	Hysteresis voltage	V _{DD} rising	0.2%	0.5%	0.8%	
IMR	MR pin internal pullup current	$V_{\overline{MR}} = 0 V$	500	620	700	nA
WATCHDO	3 FUNCTION					
I _{CWD}	CWD pin charge current	CWD = 0.5 V	337	375	413	nA
V _{CWD}	CWD pin threshold voltage		1.192	1.21	1.228	V
V _{OL}	RESET, WDO output low	VDD = 5 V, I _{SINK} = 3 mA			0.4	V
I _D	RESET, WDO output leakage current, open-drain	$VDD = V_{ITN} + V_{HYST},$ $V_{RESET} = V_{WDO} = 6.5 V$			1	μΑ
VIL	Low-level input voltage (MR, SET1)				0.25	V
V _{IH}	High-level input voltage (MR, SET1)		0.8			V
V _{IL(WDI)}	Low-level input voltage (WDI)				$0.3 \times V_{DD}$	V
V _{IH(WDI)}	High-level input voltage (WDI)		0.8 × V _{DD}			V

When V_{DD} falls below V_{UVLO}, <u>RESET</u> is driven low.
 When V_{DD} falls below V_{POR}, <u>RESET</u> and <u>WDO</u> are undefined.
 During power-on, V_{DD} must be a minimum 1.6 V for at least 300 μs before <u>RESET</u> correlates with V_{DD}.

6.6 Timing Requirements

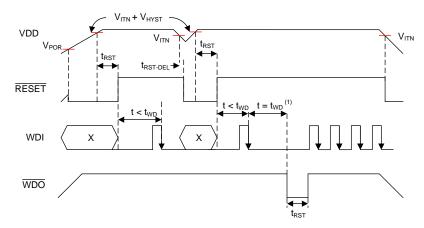
at $V_{ITN} + V_{HYST} \le V_{DD} \le 6.5$ V over the operating temperature range of $-40^{\circ}C \le T_A$, $T_J \le 125^{\circ}C$ (unless otherwise noted); the open-drain pullup resistors are 10 k Ω for each output; typical values are at $T_J = 25^{\circ}C$

			MIN	NOM	MAX	UNIT
GENER	AL	L				
t _{INIT}	CWD pin evaluation period			381		μs
	Minimum MR, SET1 pin pulse duration			1		μs
	Startup delay ⁽¹⁾			300		μs
RESET	FUNCTION					
t _{RST}	Reset timeout period		170	200	230	ms
	$V_{\rm to} \overline{\rm DFCFT}$ dology	$V_{DD} = V_{ITN} + V_{HYST} + 2.5\%$		35		
t _{RST-DEL}	V _{DD} to RESET delay	$V_{DD} = V_{ITN} - 2.5\%$		17		μs
t _{MR-DEL}	L MR to RESET delay			200		ns
WATCH	DOG FUNCTION					
		CWD = NC, SET1 = $0^{(3)}$	Watchdog disabled			
		CWD = NC, SET1 = 1 ⁽³⁾	1360	1600	1840	ms
t _{WD}	Watchdog timeout ⁽²⁾	CWD = 10 k Ω to VDD, SET1 = 0 ⁽³⁾	Watch	dog disabled		
		CWD = 10 k Ω to VDD, SET1 = 1 ⁽³⁾	170	200	230	ms
t _{WD-} setup	Setup time required for device being enabled	to respond to changes on WDI after		150		μs
	Minimum WDI pulse duration			50		ns
t _{WD-del}	WDI to WDO delay			50		ns

During power-on, V_{DD} must be a minimum 1.6 V for at least 300 µs before RESET correlates with V_{DD}. (1)

The fixed watchdog timing covers both standard and extended versions. SET1 = 0 means $V_{SET1} < V_{IL}$; SET1 = 1 means $V_{SET1} > V_{IH}$. (2)

(3)



(1) See Figure 2 for WDI timing requirements.

Figure 1. Timing Diagram



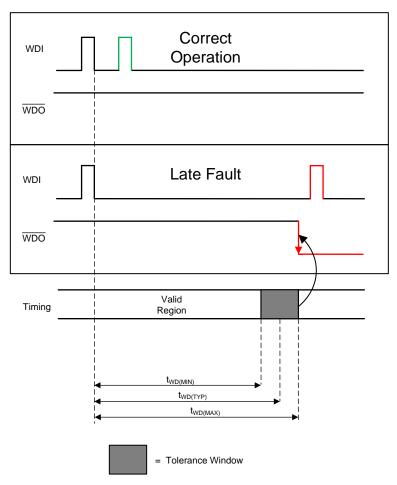


Figure 2. Watchdog Timing Diagram

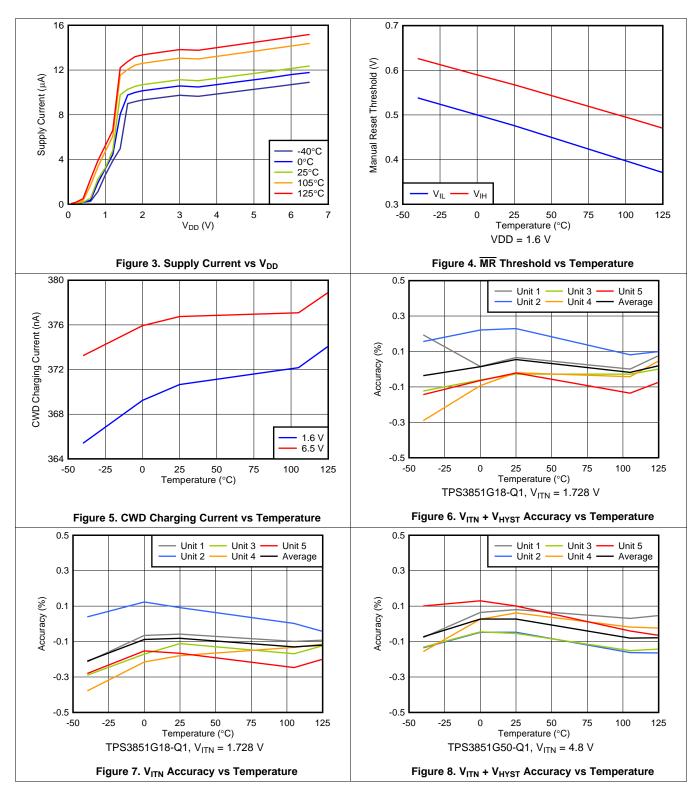
STRUMENTS

EXAS

TPS3851-Q1 SBVS286 – MARCH 2017

6.7 Typical Characteristics

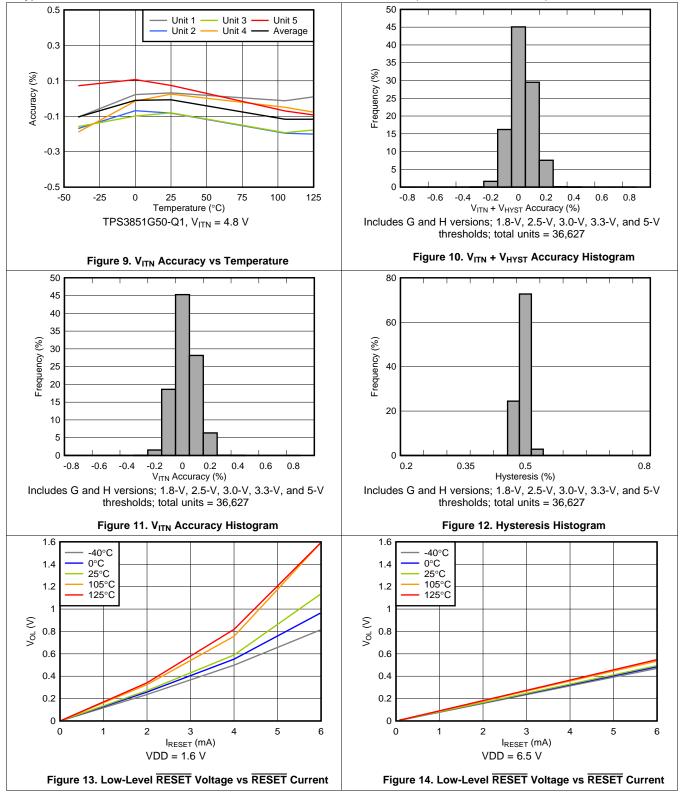
all typical characteristics curves are taken at 25°C with 1.6 V ≤ VDD ≤ 6.5 V (unless other wise noted)





Typical Characteristics (continued)

all typical characteristics curves are taken at 25°C with 1.6 V ≤ VDD ≤ 6.5 V (unless other wise noted)



SBVS286-MARCH 2017

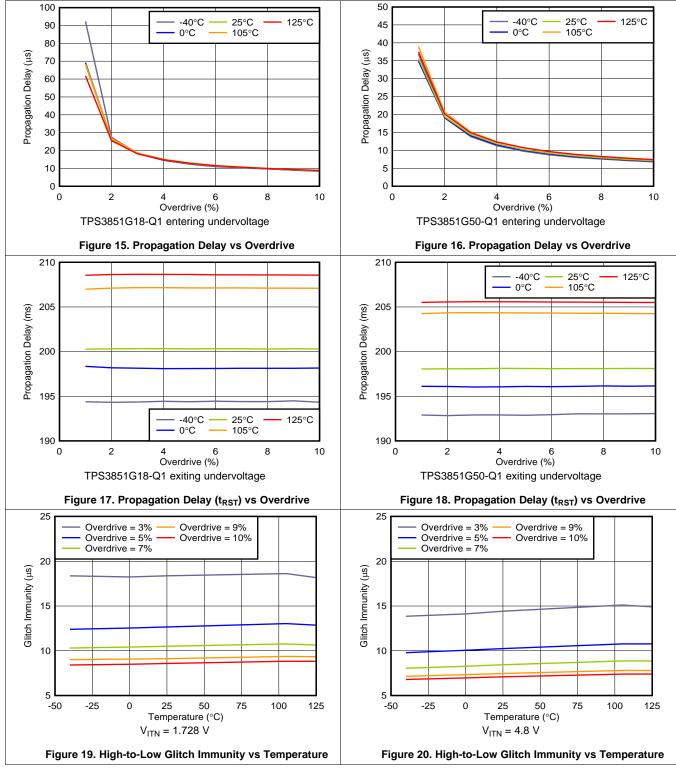
TPS3851-Q1

Texas Instruments

www.ti.com

Typical Characteristics (continued)

all typical characteristics curves are taken at 25°C with 1.6 V ≤ VDD ≤ 6.5 V (unless other wise noted)



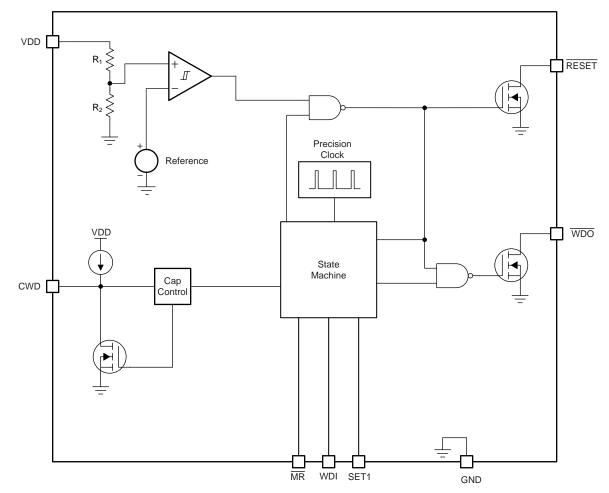


7 Detailed Description

7.1 Overview

The TPS3851-Q1 is a high-accuracy voltage supervisor with an integrated watchdog timer. This device includes a precision undervoltage supervisor with a threshold that achieves 0.8% accuracy over the specified temperature range of -40°C to +125°C. In addition, the TPS3851-Q1 includes accurate hysteresis on the threshold, making the device ideal for use with tight tolerance systems where voltage supervisors must ensure a RESET before the minimum supply tolerance of the microprocessor or system-on-a-chip (SoC) is reached. There are two options for the watchdog timing standard and extended timing. To get standard timing use the TPS3851Xyy(y)S-Q1, for extended timing use the TPS3851Xyy(y)E-Q1.

7.2 Functional Block Diagram



NOTE: $R_1 + R_2 = 4.5 M\Omega$.

7.3 Feature Description

7.3.1 **RESET**

Connect $\overline{\text{RESET}}$ to V_{PU} through a 1-k Ω to 100-k Ω pullup resistor. $\overline{\text{RESET}}$ remains high (deasserted) when V_{DD} is greater than the negative threshold voltage (V_{ITN}). If V_{DD} falls below the negative threshold (V_{ITN}), then $\overline{\text{RESET}}$ is asserted, driving the $\overline{\text{RESET}}$ pin to low impedance. When V_{DD} rises above $V_{\text{ITN}} + V_{\text{HYST}}$, a delay circuit is enabled that holds $\overline{\text{RESET}}$ low for a specified reset delay period (t_{RST}). When the reset delay has elapsed, the RESET pin goes to a high-impedance state and uses a pullup resistor to hold $\overline{\text{RESET}}$ high. The pullup resistor must be connected to the proper voltage rail to allow other devices to be connected at the correct interface voltage. To ensure proper voltage levels, give some consideration when choosing the pullup resistor values. The pullup resistor value is determined by output logic low voltage (V_{OL}), capacitive loading, leakage current (I_{D}), and the current through the $\overline{\text{RESET}}$ pin $I_{\overline{\text{RESET}}}$.

7.3.2 Manual Reset MR

The manual reset (\overline{MR}) input allows a processor or other logic circuits to initiate a reset. A logic low on \overline{MR} causes \overline{RESET} to assert. After \overline{MR} returns to a logic high and V_{DD} is above $V_{ITN} + V_{HYST}$, \overline{RESET} is deasserted after the reset delay time (t_{RST}). If \overline{MR} is not controlled externally, then \overline{MR} can either be connected to V_{DD} or left floating because the \overline{MR} pin is internally pulled up.

7.3.3 UV Fault Detection

The TPS3851-Q1 features undervoltage detection for common rails between 1.8 V and 5 V. The voltage is monitored on the input rail of the device. If V_{DD} drops below V_{ITN} , then RESET is asserted (driven low). Figure 21 shows that when V_{DD} is above $V_{ITN} + V_{HYST}$, RESET deasserts after t_{RST} . The internal comparator has built-in hysteresis that provides some noise immunity and ensures stable operation. Although not required in most cases, for noisy applications, good analog design practice is to place a 1-nF to 100-nF bypass capacitor close to the VDD pin to reduce sensitivity to transient voltages on the monitored signal.

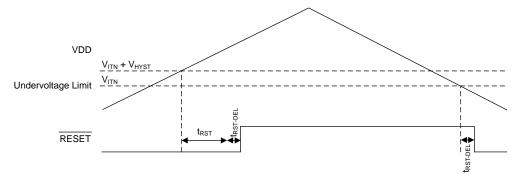


Figure 21. Undervoltage Detection

7.3.4 Watchdog Mode

This section provides information for the watchdog mode of operation.

7.3.4.1 CWD

The CWD pin provides the user the functionality of both high-precision, factory-programmed watchdog timing options and user-programmable watchdog timing. The TPS3851-Q1 features three options for setting the watchdog timer: connecting a capacitor to the CWD pin, connecting a pullup resistor to VDD, and leaving the CWD pin unconnected. The configuration of the CWD pin is evaluated by the device every time V_{DD} enters the valid region (V_{ITN} + V_{HYST} < V_{DD}). The pin evaluation is controlled by an internal state machine that determines which option is connected to the CWD pin. The sequence of events typically takes 381 μ s (t_{INIT}) to determine if the CWD pin is left unconnected, pulled-up through a resistor, or connected to a capacitor. If the CWD pin is being pulled up to VDD, a 10-k Ω resistor is required.

NSTRUMENTS

FXAS



Feature Description (continued)

7.3.4.2 Watchdog Input WDI

WDI is the watchdog timer input that controls the \overline{WDO} output. The WDI input is triggered by the falling edge of the input signal. To ensure proper functionality of the watchdog timer, always issue the WDI pulse before $t_{WD(min)}$. If the pulse is issued in this region, then \overline{WDO} remains unasserted. Otherwise, the device asserts \overline{WDO} , putting the \overline{WDO} pin into a low-impedance state.

The watchdog input (WDI) is a digital pin. In order to ensure there is no increase in I_{DD} , drive the WDI pin to either VDD or GND at all times. Putting the pin to an intermediate voltage can cause an increase in supply current (I_{DD}) because of the architecture of the digital logic gates. When RESET is asserted, the watchdog is disabled and all signals input to WDI are ignored. When RESET is no longer asserted, the device resumes normal operation and no longer ignores the signal on WDI. If the watchdog is disabled, drive the WDI pin to either VDD or GND. Figure 22 shows the valid region for a WDI pulse to be issued to prevent WDO from being triggered and pulled low.

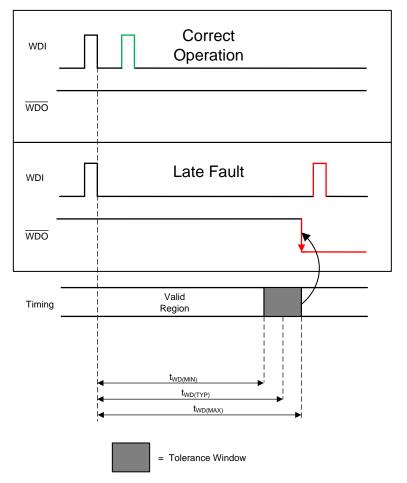


Figure 22. Watchdog Timing Diagram

7.3.4.3 Watchdog Output WDO

The TPS3851-Q1 features a watchdog timer with an independent watchdog output (\overline{WDO}). The independent watchdog output provides the flexibility to flag a <u>fault</u> in the watchdog timing without performing an entire system reset. When RESET is not asserted (high), the \overline{WDO} signal maintains normal operation. When asserted, \overline{WDO} remains low for t_{RST}. When the RESET signal is asserted (low), the \overline{WDO} pin goes to a high-impedance state. When RESET is unasserted, the watchdog timer resumes normal operation.

Copyright © 2017, Texas Instruments Incorporated



Feature Description (continued)

7.3.4.4 SET1

The SET1 pin can enable and disable the watchdog timer. If SET1 is set to GND, the watchdog timer is disabled and WDI is ignored. If the watchdog timer is disabled, drive the WDI pin to either GND or VDD to ensure that there is no increase in I_{DD} . When SET1 is logic high, the watchdog operates normally. The SET1 pin can be changed dynamically; however, if the watchdog is going from disabled to enabled (as shown in Figure 23) there is a 150-µs setup time where the watchdog does not respond to changes on WDI.

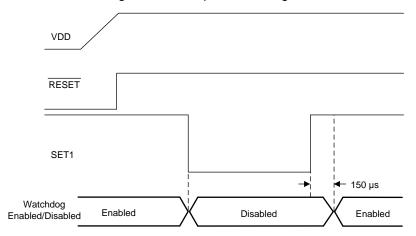


Figure 23. Enabling and Disabling the Watchdog

7.4 Device Functional Modes

Table 1 summarises the functional modes of the TPS3851-Q1.

Table 1.	Device	Functional	Modes
----------	--------	-------------------	-------

V _{DD}	WDI	WDO	RESET
V _{DD} < V _{POR}	—	—	Undefined
$V_{POR} \le V_{DD} < V_{DD(min)}$	Ignored	High	Low
$V_{DD(min)} \le V_{DD} \le V_{ITN} + V_{HYST}^{(1)}$	Ignored	High	Low
$V_{DD} > V_{ITN}^{(2)}$	$t_{PULSE} < t_{WD(min)}^{(3)}$	High	High
$V_{DD} > V_{ITN}^{(2)}$	$t_{PULSE} > t_{WD(min)}^{(3)}$	Low	High

(1) Only valid before V_{DD} has gone above $V_{ITN} + V_{HYST}$.

(2) Only valid after V_{DD} has gone above $V_{ITN} + V_{HYST}$.

(3) Where t_{pulse} is the time between the falling edges on WDI.

7.4.1 V_{DD} is Below V_{POR} ($V_{DD} < V_{POR}$)

When V_{DD} is less than V_{POR} , <u>RESET</u> is undefined and can be either high or low. The state of <u>RESET</u> largely depends on the load that the <u>RESET</u> pin is experiencing.

7.4.2 Above Power-On-Reset, But Less Than $V_{DD(min)}$ ($V_{POR} \le V_{DD} < V_{DD(min)}$)

When the voltage <u>on V_{DD} </u> is less than $V_{DD(min)}$, and greater than or equal to V_{POR} , the RESET signal is asserted (logic low). When RESET is asserted, the watchdog output WDO is in a high-impedance state regardless of the WDI signal that is input to the device.

7.4.3 Normal Operation ($V_{DD} \ge V_{DD(min)}$)

When V_{DD} is greater than or equal to $V_{DD(min)}$, the RESET signal is determined by V_{DD} . When RESET is asserted, WDO goes to a high-impedance state. WDO is then pulled high through the pullup resistor.



8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The following sections describe in detail proper device implementation, depending on the final application requirements.

8.1.1 CWD Functionality

The TPS3851-Q1 features three options for setting the watchdog timer: connecting a capacitor to the CWD pin, connecting a pullup resistor to VDD, and leaving the CWD pin unconnected. Figure 24 shows a schematic drawing of all three options. If this pin is connected to VDD through a $10-k\Omega$ pullup resistor or left unconnected (high impedance), then the factory-programmed watchdog timeouts are enabled; see the *Factory-Programmed Timing Options* section. Otherwise, the watchdog timeout can be adjusted by placing a capacitor from the CWD pin to ground.

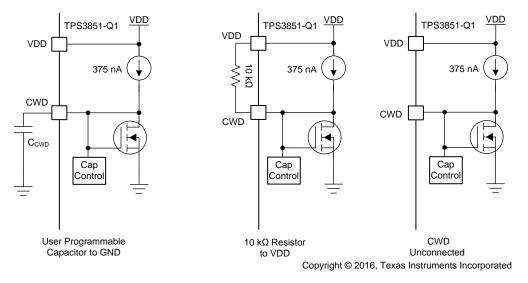


Figure 24. CWD Charging Circuit

8.1.1.1 Factory-Programmed Timing Options

If using the factory-programmed timing options (listed in Table 2), the CWD pin must either be unconnected or pulled up to VDD through a $10-k\Omega$ pullup resistor. Using these options enables high-precision, 15% accurate watchdog timing.

INF	TU	STANDARD AI			
CWD	SET1	MIN	TYP	MAX	UNIT
NC	0				
NC	1	1360	1600	1840	ms
10 k Ω to VDD	0				
10 kΩ to VDD	1	170	200	230	ms

Table 2. Factory Programmed Watchdog Timing



Application Information (continued)

8.1.1.2 Adjustable Capacitor Timing

Adjustable capacitor timing is achievable by connecting a capacitor to the CWD pin. If a capacitor is connected to CWD, then a 375-nA, constant-current source charges C_{CWD} until $V_{CWD} = 1.21$ V. Table 3 shows how to calculate t_{WD} using Equation 1, Equation 2, and the SET1 pin. The TPS3851-Q1 determines the watchdog timeout with the formulas given in Equation 1 and Equation 2, where C_{CWD} is in nanofarads and t_{WD} is in milliseconds.

$$t_{WD(standard)}$$
 (ms) = 3.23 × C_{CWD} (nF) + 0.381 (ms)

(1) (2)

 $t_{WD(extended)}(ms) = 77.4 \times C_{CWD}(nF) + 55 (ms)$

The TPS3851-Q1 is designed and tested using C_{CWD} capacitors between 100 pF and 1 µF. Equation 1 and Equation 2 are for ideal capacitors; capacitor tolerances vary the actual device timing. For the most accurate timing, use ceramic capacitors with COG dielectric material. If a C_{CWD} capacitor is used, Equation 1 can be used to set t_{WD} for standard timing. Use Equation 2 to calculate t_{WD} for extended timing. Table 4 shows the minimum and maximum calculated t_{WD} values using an ideal capacitor for both standard and extended timing.

Table 3. Programmable CWD Timing

INF	TUT	STANDAR	D TIMING WDT	(t _{WD})	EXTENDE	TIMING WDT (t _{WD})	UNIT
CWD	SET1	MIN	TYP	MAX	MIN	ТҮР	MAX	UNIT
C _{CWD}	0	Wate	chdog disabled		Wate	hdog disabled		
C _{CWD}	1	$t_{WD(std)} \times 0.85$	t _{WD(std)} ⁽¹⁾	$t_{WD(std)} \times 1.15$	$t_{WD(ext)} \times 0.85$	t _{WD(ext)} ⁽²⁾	$t_{WD(ext)} \times 1.15$	ms

(1) Calculated from Equation 1 using an ideal capacitor.

(2) Calculated from Equation 2 using an ideal capacitor.

<u> </u>	STANDARD	TIMING WDT (t	vd)	EXTENDED	vd)	UNIT						
C _{CWD}	MIN ⁽¹⁾	ТҮР	MAX ⁽¹⁾	MIN ⁽¹⁾	ТҮР	MAX ⁽¹⁾	UNIT					
100 pF	0.598	0.704	0.809	53.33	62.74	72.15	ms					
1 nF	3.069	3.611	4.153	112.5	132.4	152.3	ms					
10 nF	27.78	32.68	37.58	704.7	829	953.4	ms					
100 nF	274.9	323.4	371.9	6626	7795	8964	ms					
1 μF	2746	3230	3715	65837	77455	89073	ms					

Table 4. t_{WD} Values for Common Ideal Capacitor Values

(1) The minimum and maximum values are calculated using an ideal capacitor.



8.1.2 Overdrive Voltage

Forcing a RESET is dependent on two conditions: the amplitude V_{DD} is beyond the trip point (ΔV_1 and ΔV_2), and the length of time that the voltage is beyond the trip point (t_1 and t_2). If the voltage is just under the trip point for a long period of time, <u>RESET</u> asserts and the output is pulled low. However, if V_{DD} is just under the trip point for a few nanoseconds, RESET does not assert and the output remains high. The length of time required for RESET to assert can be changed by increasing the amount V_{DD} goes under the trip point. If V_{DD} is under the trip point by 10%, the amount of time required for the comparator to respond is much faster and causes RESET to assert much quicker than when barely under the trip point voltage. Equation 3 shows how to calculate the percentage overdrive.

$$Overdrive = |(V_{DD} / V_{ITX} - 1) \times 100\%|$$

In Equation 3, V_{ITX} corresponds to the threshold trip point. If V_{DD} is exceeding the positive threshold, $V_{ITN} + V_{HYST}$ is used. V_{ITN} is used when V_{DD} is falling below the negative threshold. In Figure 25, t_1 and t_2 correspond to the amount of time that V_{DD} is over the threshold; the propagation delay versus overdrive for V_{ITN} and $V_{ITN} + V_{HYST}$ is illustrated in Figure 16 and Figure 18, respectively.

The TPS3851-Q1 is relatively immune to short positive and negative transients on VDD because of the overdrive voltage curve.

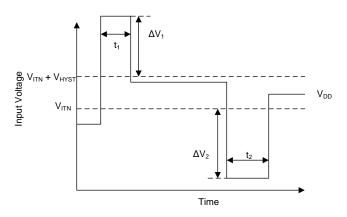


Figure 25. Overdrive Voltage

1.8 V 🔿

8.2 Typical Application



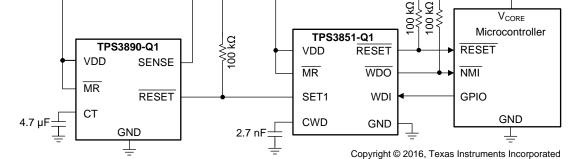


Figure 26. Monitoring the Supply Voltage and Watchdog Supervision of a Microcontroller

8.2.1 Design Requirements

PARAMETER	DESIGN REQUIREMENT	DESIGN RESULT
Watchdog disable for initialization period	Watchdog must remain disabled for 5 seconds until logic enables the watchdog timer	5.02 seconds (typ)
Output logic voltage	1.8-V CMOS	1.8-V CMOS
Monitored rail	1.8 V with a 5% threshold	Worst-case $V_{ITN} = 1.714 \text{ V} - 4.7\%$
Watchdog timeout	10 ms, typical	$t_{WD(min)}$ = 7.3 ms, $t_{WD(TYP)}$ = 9.1 ms, $t_{WD(max)}$ = 11 ms
Maximum device current consumption	50 μΑ	37 μ A when RESET or WDO is asserted ⁽¹⁾

(1) Only includes the TPS3851G18S-Q1 current consumption.

8.2.2 Detailed Design Procedure

8.2.2.1 Monitoring the 1.8-V Rail

The undervoltage comparator allows for precise voltage supervision of common rails between 1.8 V and 5.0 V. This application calls for very tight monitoring of the rail with only 5% of variation allowed on the rail. To ensure this requirement is met, the TPS3851G18S-Q1 was chosen for its -4% threshold. To calculate the worst-case for V_{ITN}, the accuracy must also be taken into account. Use Equation 4 to calculate the worst-case for V_{ITN}:

 $V_{\text{ITN(Worst Case)}} = V_{\text{ITN(typ)}} \times 0.992 = 1.8 \times 0.96 \times 0.992 = 1.714 \text{ V}$

(4)



www.ti.com



8.2.2.2 Calculating the RESET and WDO Pullup Resistor

Figure 27 shows the TPS3851-Q1 using an open-drain configuration for the RESET circuit. When the FET is off, the resistor pulls the drain of the transistor to VDD and when the FET is turned on, the FET attempts to pull the drain to ground, thus creating an effective resistor divider. The resistors in this divider must be chosen to ensure that V_{OL} is below the maximum value. To choose the proper pullup resistor, there are three key specifications to keep in mind: the pullup voltage (V_{PU}), the recommended maximum RESET pin current (I_{RESET}), and V_{OL} . The maximum V_{OL} is 0.4 V, meaning that the effective resistor divider created must be able to bring the voltage on the reset pin below 0.4 V with I_{RESET} kept below 10 mA. For this example, with a V_{PU} of 1.8 V, a resistor must be chosen to keep I_{RESET} below 50 μ A because this value is the maximum consumption current allowed. To ensure this specification is met, a pullup resistor value of 100 k Ω was selected, which sinks a maximum of 18 μ A when RESET or WDO is asserted. As illustrated in Figure 13, the RESET current is at 18 μ A and the low-level output voltage is approximately zero.

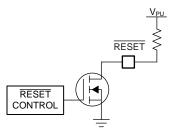


Figure 27. RESET Open-Drain Configuration

8.2.2.3 Setting the Watchdog

As illustrated in Figure 24 there are three options for setting the watchdog timer. The design specifications in this application require the programmable timing option (external capacitor connected to CWD). When a capacitor is connected to the CWD pin, the watchdog timer is governed by Equation 1 for the standard timing version. However, only the standard version is capable of meeting this timing requirement. Equation 1 is only valid for ideal capacitors, any temperature or voltage derating must be accounted for separately.

$$C_{CWD}$$
 (nF) = (t_{WD}(ms) - 0.0381) / 3.23 = (10 - 0.381) / 3.23 = 2.97 nF (5)

The nearest standard capacitor value to 2.9 nF is 2.7 nF. Selecting 2.7 nF for the C_{CWD} capacitor gives the following minimum timing parameters:

$$t_{WD(MIN)} = 0.85 \times t_{WD(TYP)} = 0.85 \times (3.23 \times 2.7 + 0.381) = 7.73 \text{ ms}$$
(6)

$$t_{WD(MAX)} = 1.15 \times t_{WD(TYP)} = 1.15 \times (3.23 \times 2.7 + 0.381) = 10.46 \text{ ms}$$
(7)

Capacitor tolerance also influences $t_{WD(MIN)}$ and $t_{WD(MAX)}$. Select a ceramic COG dielectric capacitor for high accuracy. For 2.7 nF, COG capacitors are readily available with 5% tolerances. This selection results in a 5% decrease in $t_{WD(MIN)}$ and a 5% increase in $t_{WD(MAX)}$, giving 7.34 ms and 11 ms, respectively. To ensure proper functionality, a falling edge must be issued before $t_{WD(min)}$. Figure 29 illustrates that a WDI signal with a period of 5 ms keeps WDO from asserting.

TPS3851-Q1

SBVS286-MARCH 2017



www.ti.com

8.2.2.4 Watchdog Disabled During Initialization Period

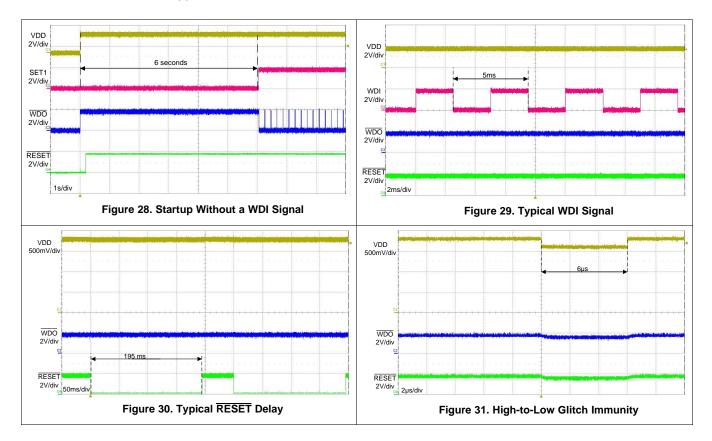
The watchdog is often needed to be disabled during startup to allow for an initialization period. When the initialization period is over, the watchdog timer is turned back on to allow the microcontroller to be monitored by the TPS3851-Q1. To achieve this setup, SET1 must start at GND. In this design, SET1 is controlled by a TPS3890-Q1 supervisor. In this application, the TPS3890-Q1 was chosen to monitor VDD as well, which means that the RESET on the TPS3890-Q1 stays low until V_{DD} rises above V_{ITN}. When VDD comes up, the delay time can be adjusted through the CT capacitor on the TPS3890-Q1. With this approach, the RESET delay can be adjusted from a minimum of 25 μ s to a maximum of 30 seconds. For this design, a typical delay of 5 seconds is needed before the watchdog timer is enabled. The CT capacitor calculation (see the TPS3890-Q1 data sheet) yields an ideal capacitance of 4.67 μ F, giving a closest standard ceramic capacitor value of 4.7 μ F. When the watchdog is disabled, the WDO output remains high. However when SET1 goes high and there is no WDI signal, WDO begins to assert. See the TPS3890-Q1 data sheet for detailed information on the TPS3890-Q1.

8.2.3 Glitch Immunity

Figure 31 shows the high-to-low glitch immunity for the TPS3851G18S-Q1 with a 7% overdrive with V_{DD} starting at 1.8 V. This curve shows that V_{DD} can go below the threshold for at least 6 µs before RESET asserts.

8.2.4 Application Curves

Unless otherwise stated, application curves were taken at $T_A = 25^{\circ}C$.





9 Power Supply Recommendations

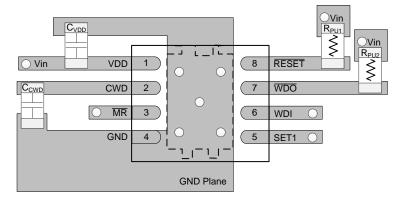
This device is designed to operate from an input supply with a voltage range between 1.6 V and 6.5 V. An input supply capacitor is not required for this device; however, if the input supply is noisy, then good analog practice is to place a $0.1-\mu$ F capacitor between the VDD pin and the GND pin.

10 Layout

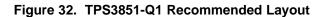
10.1 Layout Guidelines

- Make sure that the connection to the VDD pin is low impedance. Good analog design practice is to place a 0.1-µF ceramic capacitor as near as possible to the VDD pin.
- If a C_{CWD} capacitor or pullup resistor is used, place these components as close as possible to the CWD pin. If the CWD pin is left unconnected, make sure to minimize the amount of parasitic capacitance on the pin.
- Place the pullup resistors on RESET and WDO as close to the pin as possible.

10.2 Layout Example



Denotes a via



G

н

18

25

30

33

50

S

Е

11.1 Device Support

11.1.1 Device Nomenclature

Х

DESCRIPTION

TPS3851-Q1 (high-accuracy supervisor with watchdog)

(nominal threshold as a percent of the nominal

monitored voltage)

yy(y)

(nominal monitored voltage option)

z (nominal watchdog timeout period)

11 Device and Documentation Support

11.2 Documentation Support

11.2.1 Related Documentation

For related documentation see the following:

- TPS3890 Low Quiescent Current, 1% Accurate Supervisor with Programmable Delay
- TPS3851EVM-780 Evaluation Module

11.3 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

11.4 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E[™] Online Community *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support TI's Design Support Quickly find helpful E2E forums along with design support tools and contact information for technical support.

11.5 Trademarks

E2E is a trademark of Texas Instruments. All other trademarks are the property of their respective owners.

11.6 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

VALUE

 $V_{ITN} = -4\%$

 $V_{ITN} = -7\%$

1.8 V

2.5 V

3.0 V

3.3 V

5.0 V

 t_{WD} (ms) = 3.23 x C_{WD} (nF) + 0.381 (ms)

 t_{WD} (ms) = 77.4 x C_{WD} (nF) + 55.2 (ms)

STRUMENTS

www.ti.com



11.7 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



10-Dec-2020

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
TPS3851G18EQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851DF	Samples
TPS3851G18SQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851DE	Samples
TPS3851G25EQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851EF	Samples
TPS3851G25SQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851EE	Samples
TPS3851G30EQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851FF	Samples
TPS3851G30SQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851FE	Samples
TPS3851G33EQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851GF	Samples
TPS3851G33SQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851GE	Samples
TPS3851G50EQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851HF	Samples
TPS3851G50SQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851HE	Samples
TPS3851H18EQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851LF	Samples
TPS3851H18SQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851LE	Samples
TPS3851H25EQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851MF	Samples
TPS3851H25SQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851ME	Samples
TPS3851H30EQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851NF	Samples
TPS3851H30SQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851NE	Samples
TPS3851H33EQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851PF	Samples
TPS3851H33SQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851PE	Samples
TPS3851H50EQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851RF	Samples
TPS3851H50SQDRBRQ1	ACTIVE	SON	DRB	8	3000	RoHS & Green	SN	Level-2-260C-1 YEAR	-40 to 125	851RE	Samples



10-Dec-2020

(1) The marketing status values are defined as follows:
 ACTIVE: Product device recommended for new designs.
 LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
 NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
 PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
 OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <= 1000ppm threshold. Antimony trioxide based flame retardants must also meet the <= 1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

⁽⁴⁾ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer:The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

OTHER QUALIFIED VERSIONS OF TPS3851-Q1 :

Catalog: TPS3851

NOTE: Qualified Version Definitions:

• Catalog - TI's standard catalog product

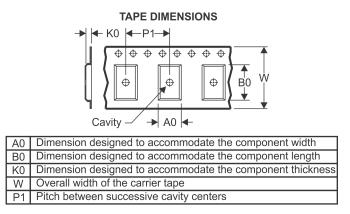
PACKAGE MATERIALS INFORMATION

www.ti.com

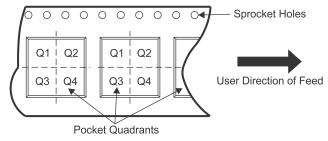
Texas Instruments

TAPE AND REEL INFORMATION





QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS3851G18EQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851G18SQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851G25EQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851G25SQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851G30EQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851G30SQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851G33EQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851G33SQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851G50EQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851G50SQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851H18EQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851H18SQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851H25EQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851H25SQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851H30EQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851H30SQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851H33EQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851H33SQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2

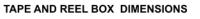
PACKAGE MATERIALS INFORMATION

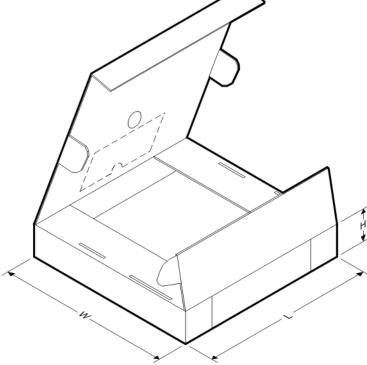


www.ti.com

5-Jan-2021

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS3851H50EQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2
TPS3851H50SQDRBRQ1	SON	DRB	8	3000	330.0	12.4	3.3	3.3	1.0	8.0	12.0	Q2





*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS3851G18EQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851G18SQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851G25EQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851G25SQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851G30EQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851G30SQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851G33EQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851G33SQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851G50EQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851G50SQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851H18EQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851H18SQDRBRQ1	SON	DRB	8	3000	370.0	355.0	55.0
TPS3851H25EQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851H25SQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851H30EQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0

PACKAGE MATERIALS INFORMATION



www.ti.com

5-Jan-2021

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS3851H30SQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851H33EQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851H33SQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851H50EQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0
TPS3851H50SQDRBRQ1	SON	DRB	8	3000	367.0	367.0	38.0

GENERIC PACKAGE VIEW

VSON - 1 mm max height PLASTIC SMALL OUTLINE - NO LEAD



Images above are just a representation of the package family, actual package may vary. Refer to the product data sheet for package details.

4203482/L



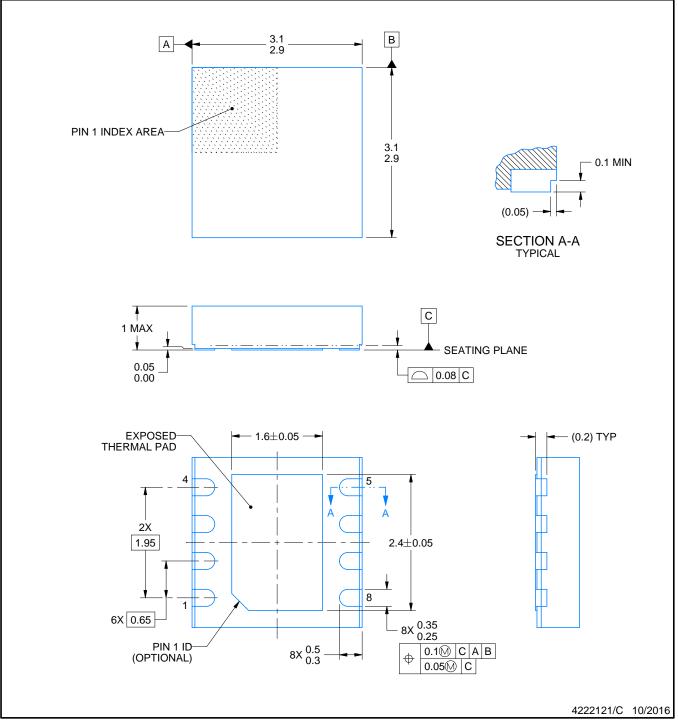
DRB0008F



PACKAGE OUTLINE

VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.

3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.

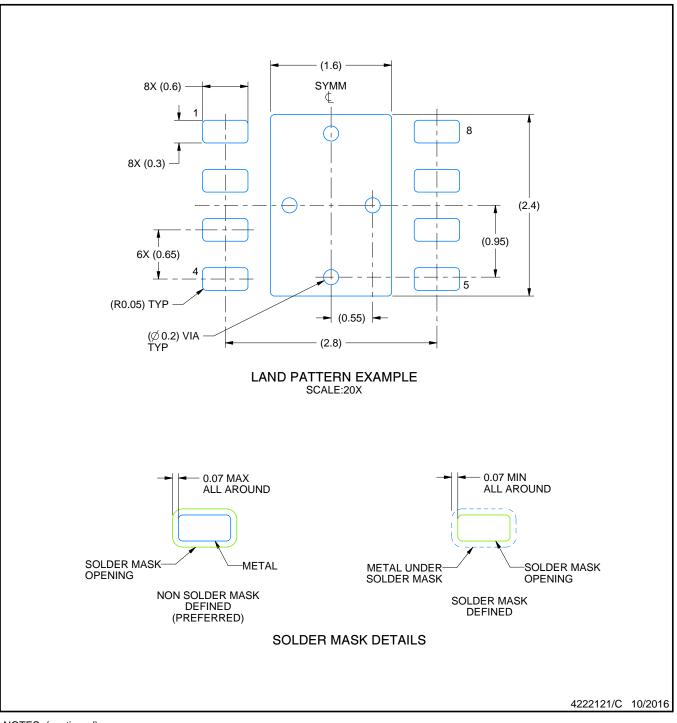


DRB0008F

EXAMPLE BOARD LAYOUT

VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

- This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).
- Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

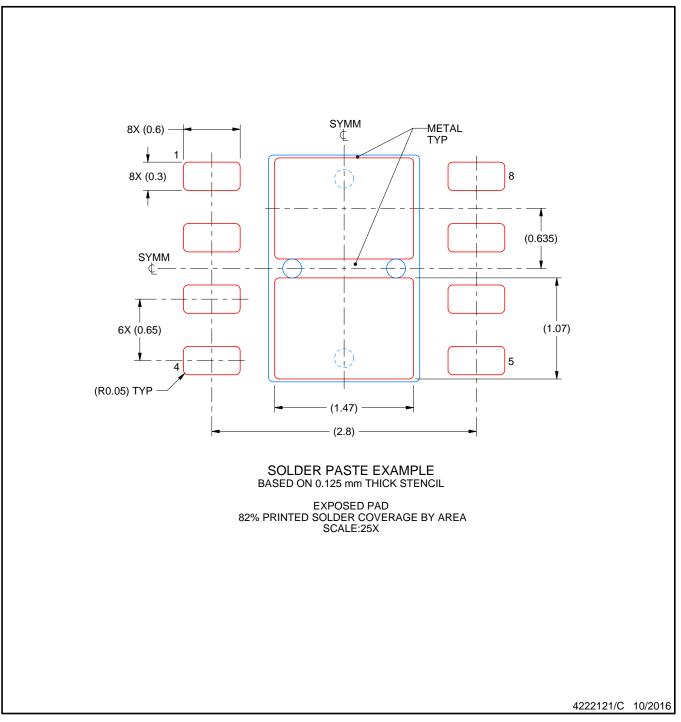


DRB0008F

EXAMPLE STENCIL DESIGN

VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, or other requirements. These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale (https://www.ti.com/legal/termsofsale.html) or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2021, Texas Instruments Incorporated